

COUPLED FIXED POINT THEOREMS IN G_b -METRIC SPACES

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Abstract. T. G. Bhaskar and V. Lakshmikantham [Fixed point theorems in partially ordered metric spaces and applications, *Nonlinear Anal.* 65 (2006) 1379–1393], V. Lakshmikantham and Lj. B. Ćirić [Coupled fixed point theorems for nonlinear contractions in partially ordered metric spaces, *Nonlinear Anal.* 70 (2009) 4341–4349] introduced the concept of a coupled coincidence point of a mapping F from $X \times X$ into X and a mapping g from X into X . In this paper we prove a coupled coincidence fixed point theorem in the setting of a generalized b -metric space. Three examples are presented to verify the effectiveness and applicability of our main result.

1. Introduction

Mustafa and Sims [25] introduced a new notion of generalized metric space called a G -metric space. Mustafa, Sims and others studied fixed point theorems for mappings satisfying different contractive conditions [1, 2, 6, 10, 11, 19, 22, 23, 25, 27, 28, 32, 35, 36, 39]. Abbas and Rhoades [1] obtained some common fixed point theorems for non-commuting maps without continuity satisfying different contractive conditions in the setting of generalized metric spaces. Lakshmikantham et al. in [7, 21] introduced the concept of a coupled coincidence point for a mapping F from $X \times X$ into X and a mapping g from X into X , and studied coupled fixed point theorems in partially ordered metric spaces. In [33], Sedghi et al. proved a coupled fixed point theorem for contractive mappings in complete fuzzy metric spaces. On the other hand, the concept of b -metric space was introduced by Czerwik in [13]. After that, several interesting results for the existence of fixed point for single-valued and multivalued operators in b -metric spaces have been obtained [3, 5, 8, 9, 12, 14, 15, 16, 18, 20, 30, 31, 34, 37, 38]. Pacurar [29] proved some results on sequences of almost contractions and fixed points in b -metric spaces. Recently, Hussain and Shah [17] obtained results on KKM mappings in cone b -metric spaces.

Aghajani et al., in a submitted paper [4], extended the notion of G -metric space to the concept of G_b -metric space. Very recently, Mustafa et al. [24] have obtained

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some coupled coincidence point theorems for nonlinear (ψ, φ) -weakly contractive mappings in partially ordered G_b -metric spaces.

In this paper, we prove a coupled coincidence fixed point theorem in the setting of a generalized b -metric space. First, we present some basic properties of G_b -metric spaces.

Following is the definition of generalized b -metric spaces or G_b -metric spaces.

DEFINITION 1.1. [24] Let X be a nonempty set and $s \geq 1$ be a given real number. Suppose that a mapping $G : X \times X \times X \rightarrow \mathbb{R}^+$ satisfies:

$$(G_b1) \quad G(x, y, z) = 0 \text{ if } x = y = z,$$

$$(G_b2) \quad 0 < G(x, x, y) \text{ for all } x, y \in X \text{ with } x \neq y,$$

$$(G_b3) \quad G(x, x, y) \leq G(x, y, z) \text{ for all } x, y, z \in X \text{ with } y \neq z,$$

$$(G_b4) \quad G(x, y, z) = G(p\{x, y, z\}), \text{ where } p \text{ is a permutation of } x, y, z \text{ (symmetry),}$$

$$(G_b5) \quad G(x, y, z) \leq s(G(x, a, a) + G(a, y, z)) \text{ for all } x, y, z, a \in X \text{ (rectangle inequality).}$$

Then G is called a generalized b -metric and the pair (X, G) is called a generalized b -metric space or G_b -metric space.

It should be noted that the class of G_b -metric spaces is effectively larger than that of G -metric spaces given in [25]. Indeed, each G -metric space is a G_b -metric space with $s = 1$. The following example shows that a G_b -metric on X need not be a G -metric on X .

EXAMPLE 1.1. [24] Let (X, G) be a G -metric space, and $G_*(x, y, z) = G^p(x, y, z)$, where $p > 1$ is a real number. Note that G_* is a G_b -metric with $s = 2^{p-1}$. In [24], it is proved that (X, G_*) is not necessarily a G -metric space.

EXAMPLE 1.2. [24] Let $X = \mathbb{R}$ and $d(x, y) = |x - y|^2$. We know that (X, d) is a b -metric space with $s = 2$. Let $G(x, y, z) = d(x, y) + d(y, z) + d(z, x)$, then (X, G) is not a G_b -metric space.

However, $G(x, y, z) = \max\{d(x, y), d(y, z), d(z, x)\}$ is a G_b -metric on \mathbb{R} with $s = 2$. Similarly, if $d(x, y) = |x - y|^p$ is selected with $p \geq 1$, then $G(x, y, z) = \max\{d(x, y), d(y, z), d(z, x)\}$ is a G_b -metric on \mathbb{R} with $s = 2^{p-1}$.

Now we present some definitions and propositions in G_b -metric spaces.

DEFINITION 1.2. [24] A G_b -metric G is said to be symmetric if $G(x, y, y) = G(y, x, x)$ for all $x, y \in X$.

DEFINITION 1.3. [24] Let (X, G) be a G_b -metric space. Then, for $x_0 \in X$, $r > 0$, the G_b -ball with center x_0 and radius r is

$$B_G(x_0, r) = \{y \in X \mid G(x_0, y, y) < r\}.$$

DEFINITION 1.4. [24] Let X be a G_b -metric space and let $d_G(x, y) = G(x, y, y) + G(x, x, y)$. Then d_G defines a b -metric on X , which is called the b -metric associated with G .

PROPOSITION 1.2. [24] *Let X be a G_b -metric space. For any $x_0 \in X$ and $r > 0$, if $y \in B_G(x_0, r)$ then there exists a $\delta > 0$ such that $B_G(y, \delta) \subseteq B_G(x_0, r)$.*

From the above proposition the family of all G_b -balls

$$\Lambda = \{B_G(x, r) \mid x \in X, r > 0\}$$

is a base of a topology $\tau(G)$ on X , which is called the G_b -metric topology.

DEFINITION 1.5. [24] Let X be a G_b -metric space. A sequence (x_n) in X is said to be:

- (1) G_b -Cauchy sequence if, for each $\varepsilon > 0$, there exists a positive integer n_0 such that, for all $m, n, l \geq n_0$, $G(x_n, x_m, x_l) < \varepsilon$;
- (2) G_b -convergent to a point $x \in X$ if, for each $\varepsilon > 0$, there exists a positive integer n_0 such that, for all $m, n \geq n_0$, $G(x_n, x_m, x) < \varepsilon$.

Using the above definitions, one can easily prove the following proposition.

PROPOSITION 1.4. [24] *Let X be a G_b -metric space and (x_n) be a sequence in X . Then the following are equivalent:*

- (1) *the sequence (x_n) is G_b -Cauchy;*
- (2) *for any $\varepsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that $G(x_n, x_m, x_m) < \varepsilon$, for all $m, n \geq n_0$.*

DEFINITION 1.6. [24] A G_b -metric space X is called complete if every G_b -Cauchy sequence is G_b -convergent in X .

Mustafa and Sims proved that each G -metric function $G(x, y, z)$ is jointly continuous in all three of its variables (see [26, Proposition 8]). But in general a G_b -metric function $G(x, y, z)$ for $s > 1$ is not jointly continuous in all three of its variables. Now we recall an example of a discontinuous G_b -metric.

EXAMPLE 1.3. [24] Let $X = \mathbb{N} \cup \{\infty\}$ and let $D : X \times X \rightarrow \mathbb{R}^+$ be defined by

$$D(m, n) = \begin{cases} 0, & \text{if } m = n, \\ \left| \frac{1}{m} - \frac{1}{n} \right|, & \text{if one of } m, n \text{ is even and the other is even or } \infty, \\ 5, & \text{if one of } m, n \text{ is odd and the other is odd (and } m \neq n) \\ & \text{or } \infty, \\ 2, & \text{otherwise.} \end{cases}$$

Then it is easy to see that for all $m, n, p \in X$, we have

$$D(m, p) \leq \frac{5}{2}(D(m, n) + D(n, p)).$$

Thus, (X, D) is a b -metric space with $s = \frac{5}{2}$ (see [16, Example 2]). Let $G(x, y, z) = \max\{D(x, y), D(y, z), D(z, x)\}$. It is easy to see that G is a G_b -metric with $s = \frac{5}{2}$. In [24], it is proved that $G(x, y, z)$ is not a continuous function.

DEFINITION 1.7. Let (X, G) and (X', G') be G_b -metric spaces, and let $f : X \rightarrow X'$ be a mapping. Then f is said to be continuous at a point $a \in X$ if and only if for every $\varepsilon > 0$, there is $\delta > 0$ such that $x, y \in X$ and $G(a, x, y) < \delta$ implies $G'(f(a), f(x), f(y)) < \varepsilon$. A function f is continuous at X if and only if it is continuous at all $a \in X$.

DEFINITION 1.8. [7] Let X be a nonempty set. An element $(x, y) \in X \times X$ is called a coupled fixed point of a mapping $F : X \times X \rightarrow X$ if $F(x, y) = x$ and $F(y, x) = y$.

DEFINITION 1.9. [21] Let X be a nonempty set. An element $(x, y) \in X \times X$ is called a coupled coincidence point of mappings $F : X \times X \rightarrow X$ and $g : X \rightarrow X$ if $F(x, y) = gx$ and $F(y, x) = gy$.

DEFINITION 1.10. [21] Let X be a nonempty set. Then we say that the mappings $F : X \times X \rightarrow X$ and $g : X \rightarrow X$ are commutative if $gF(x, y) = F(gx, gy)$.

2. Common fixed point results

Let Φ denote the class of all functions $\phi : [0, \infty) \rightarrow [0, \infty)$ such that ϕ is increasing, continuous, $\phi(t) < \frac{t}{2}$ for all $t > 0$ and $\phi(0) = 0$. It is easy to see that for every $\phi \in \Phi$ we can choose a $0 < k < \frac{1}{2}$ such that $\phi(t) \leq kt$.

We start our work by proving the following two crucial lemmas.

LEMMA 2.1. Let (X, G) be a G_b -metric space with $s \geq 1$, and suppose that (x_n) is G_b -convergent to x . Then we have

$$\frac{1}{s}G(x, y, y) \leq \liminf_{n \rightarrow \infty} G(x_n, y, y) \leq \limsup_{n \rightarrow \infty} G(x_n, y, y) \leq sG(x, y, y).$$

In particular, if $x = y$, then we have $\lim_{n \rightarrow \infty} G(x_n, y, y) = 0$.

Proof. Using the rectangle inequality in (X, G) , it is easy to see that

$$G(x_n, y, y) \leq sG(x_n, x, x) + sG(x, y, y),$$

and

$$\frac{1}{s}G(x, y, y) \leq G(x, x_n, x_n) + G(x_n, y, y).$$

Taking the upper limit as $n \rightarrow \infty$ in the first inequality and the lower limit as $n \rightarrow \infty$ in the second inequality we obtain the desired result. ■

LEMMA 2.2. Let (X, G) be a G_b -metric space and let $F : X \times X \rightarrow X$ and $g : X \rightarrow X$ be two mappings such that

$$G(F(x, y), F(u, v), F(z, w)) \leq \phi(G(gx, gu, gz) + G(gy, gv, gw)) \tag{1}$$

for some $\phi \in \Phi$ and for all $x, y, z, w, u, v \in X$. Assume that (x, y) is a coupled coincidence point of the mappings F and g . Then

$$F(x, y) = gx = gy = F(y, x).$$

Proof. Since (x, y) is a coupled coincidence point of the mappings F and g , we have $gx = F(x, y)$ and $gy = F(y, x)$. Assume $gx \neq gy$. Then by (1), we get

$$G(gx, gy, gy) = G(F(x, y), F(y, x), F(y, x)) \leq \phi(G(gx, gy, gy) + G(gy, gx, gx)).$$

Also by (1), we have

$$G(gy, gx, gx) = G(F(y, x), F(x, y), F(x, y)) \leq \phi(G(gy, gx, gx) + G(gx, gy, gy)).$$

Therefore

$$G(gx, gy, gy) + G(gy, gx, gx) \leq 2\phi(G(gx, gy, gy) + G(gy, gx, gx)).$$

Since $\phi(t) < \frac{t}{2}$, we get

$$G(gx, gy, gy) + G(gy, gx, gx) < G(gx, gy, gy) + G(gy, gx, gx),$$

which is a contradiction. So $gx = gy$, and hence $F(x, y) = gx = gy = F(y, x)$. ■

The following is the main result of this section.

THEOREM 2.1. *Let (X, G) be a complete G_b -metric space. Let $F : X \times X \rightarrow X$ and $g : X \rightarrow X$ be two mappings such that*

$$G(F(x, y), F(u, v), F(z, w)) \leq \frac{1}{s^2}\phi(G(gx, gu, gz) + G(gy, gv, gw)) \quad (2)$$

for some $\phi \in \Phi$ and all $x, y, z, w, u, v \in X$. Assume that F and g satisfy the following conditions:

1. $F(X \times X) \subseteq g(X)$,
2. $g(X)$ is complete, and
3. g is continuous and commutes with F .

Then there is a unique x in X such that $gx = F(x, x) = x$.

Proof. Let $x_0, y_0 \in X$. Since $F(X \times X) \subseteq g(X)$, we can choose $x_1, y_1 \in X$ such that $gx_1 = F(x_0, y_0)$ and $gy_1 = F(y_0, x_0)$. Again since $F(X \times X) \subseteq g(X)$, we can choose $x_2, y_2 \in X$ such that $gx_2 = F(x_1, y_1)$ and $gy_2 = F(y_1, x_1)$. Continuing this process, we can construct two sequences (x_n) and (y_n) in X such that $gx_{n+1} = F(x_n, y_n)$ and $gy_{n+1} = F(y_n, x_n)$. For $n \in \mathbb{N} \cup \{0\}$, by (2) we have

$$\begin{aligned} G(gx_{n-1}, gx_n, gx_n) &= G(F(x_{n-2}, y_{n-2}), F(x_{n-1}, y_{n-1}), F(x_{n-1}, y_{n-1})) \\ &\leq \frac{1}{s^2}\phi(G(gx_{n-2}, gx_{n-1}, gx_{n-1}) + G(gy_{n-2}, gy_{n-1}, gy_{n-1})). \end{aligned}$$

Similarly, by (2) we have

$$\begin{aligned} G(gy_{n-1}, gy_n, gy_n) &= G(F(y_{n-2}, x_{n-2}), F(y_{n-1}, x_{n-1}), F(y_{n-1}, x_{n-1})) \\ &\leq \frac{1}{s^2}\phi(G(gy_{n-2}, gy_{n-1}, gy_{n-1}) + G(gx_{n-2}, gx_{n-1}, gx_{n-1})). \end{aligned}$$

Hence, we have that

$$\begin{aligned} a_n &:= G(gx_{n-1}, gx_n, gx_n) + G(gy_{n-1}, gy_n, gy_n) \\ &\leq \frac{2}{s^2} \phi(G(gx_{n-2}, gx_{n-1}, gx_{n-1}) + G(gy_{n-2}, gy_{n-1}, gy_{n-1})) \\ &= \frac{2}{s^2} \phi(a_{n-1}) \end{aligned}$$

holds for all $n \in \mathbb{N}$. Thus, we get a k , $0 < k < \frac{1}{2}$ such that

$$a_n \leq \frac{2}{s^2} \phi(a_{n-1}) \leq \frac{2k}{s^2} a_{n-1} \leq \frac{2k}{s} a_{n-1} = qa_{n-1},$$

for $q = \frac{2k}{s}$. Hence we have

$$a_n \leq \frac{2k}{s} a_{n-1} \leq \cdots \leq \left(\frac{2k}{s}\right)^n a_0.$$

Let $m, n \in \mathbb{N}$ with $m > n$. By Axiom G_b5 of definition of G_b -metric spaces, we have

$$\begin{aligned} &G(gx_{n-1}, gx_m, gx_m) + G(gy_{n-1}, gy_m, gy_m) \\ &\leq s(G(gx_{n-1}, gx_n, gx_n) + G(gx_n, gx_m, gx_m)) \\ &\quad + s(G(gy_{n-1}, gy_n, gy_n) + G(gy_n, gy_m, gy_m)) \\ &= s(G(gx_{n-1}, gx_n, gx_n) + G(gy_{n-1}, gy_n, gy_n)) \\ &\quad + s(G(gx_n, gx_m, gx_m) + G(gy_n, gy_m, gy_m)) \\ &\leq \\ &\vdots \\ &\leq sa_n + s^2 a_{n+1} + s^3 a_{n+2} + \cdots + s^{m-n} a_{m-1} + s^{m-n} a_m \\ &\leq sq^n a_0 + s^2 q^{n+1} a_0 + \cdots + s^{m-n} q^{m-1} a_0 + s^{m-n} q^m a_0 \\ &\leq sq^n a_0 (1 + sq + s^2 q^2 + \cdots) \\ &\leq \frac{sq^n a_0}{1 - sq} \longrightarrow 0, \end{aligned}$$

since $sq = 2k < 1$. Thus (gx_n) and (gy_n) are G_b -Cauchy in $g(X)$. Since $g(X)$ is complete, we get (gx_n) and (gy_n) are G_b -convergent to some $x \in X$ and $y \in X$ respectively. Since g is continuous, we have that (ggx_n) is G_b -convergent to gx and (ggy_n) is G_b -convergent to gy . Also, since g and F commute, we have

$$ggx_{n+1} = g(F(x_n, y_n)) = F(gx_n, gy_n),$$

and

$$ggy_{n+1} = g(F(y_n, x_n)) = F(gy_n, gx_n).$$

Thus

$$\begin{aligned} G(ggx_{n+1}, F(x, y), F(x, y)) &= G(F(gx_n, gy_n), F(x, y), F(x, y)) \\ &\leq \frac{1}{s^2} \phi(G(ggx_n, gx, gx) + G(ggy_n, gy, gy)). \end{aligned}$$

Letting $n \rightarrow \infty$, and using Lemma 2.1, we get that

$$\begin{aligned} \frac{1}{s}G(gx, F(x, y), F(x, y)) &\leq \limsup_{n \rightarrow \infty} G(F(gx_n, gy_n), F(x, y), F(x, y)) \\ &\leq \limsup_{n \rightarrow \infty} \frac{1}{s^2} \phi(G(ggx_n, gx, gx) + G(ggy_n, gy, gy)) \\ &\leq \frac{1}{s^2} \phi(s(G(gx, gx, gx) + G(gy, gy, gy))) = 0. \end{aligned}$$

Hence, $gx = F(x, y)$. Similarly, we may show that $gy = F(y, x)$. By Lemma 2.2, (x, y) is a coupled fixed point of the mappings F and g , i.e.,

$$gx = F(x, y) = F(y, x) = gy.$$

Thus, using Lemma 2.1 we have

$$\begin{aligned} \frac{1}{s}G(x, gx, gx) &\leq \limsup_{n \rightarrow \infty} G(gx_{n+1}, gx, gx) \\ &= \limsup_{n \rightarrow \infty} G(F(x_n, y_n), F(x, y), F(x, y)) \\ &\leq \limsup_{n \rightarrow \infty} \frac{1}{s^2} \phi(G(gx_n, gx, gx) + G(gy_n, gy, gy)) \\ &\leq \frac{1}{s^2} \phi(s(G(x, gx, gx) + G(y, gy, gy))). \end{aligned}$$

Hence, we get

$$G(x, gx, gx) \leq \frac{1}{s} \phi(s(G(x, gx, gx) + G(y, gy, gy))).$$

Similarly, we may show that

$$G(y, gy, gy) \leq \frac{1}{s} \phi(s(G(x, gx, gx) + G(y, gy, gy))).$$

Thus,

$$\begin{aligned} G(x, gx, gx) + G(y, gy, gy) &\leq \frac{2}{s} \phi(s(G(x, gx, gx) + G(y, gy, gy))) \\ &\leq 2kG(x, gx, gx) + G(y, gy, gy). \end{aligned}$$

Since $2k < 1$, the last inequality happens only if $G(x, gx, gx) = 0$ and $G(y, gy, gy) = 0$. Hence $x = gx$ and $y = gy$. Thus we get

$$gx = F(x, x) = x.$$

To prove the uniqueness, let $z \in X$ with $z \neq x$ such that

$$z = gz = F(z, z).$$

Then

$$\begin{aligned} G(x, z, z) &= G(F(x, x), F(z, z), F(z, z)) \leq \frac{1}{s^2} \phi(2G(gx, gz, gz)) \\ &< \frac{1}{s^2} 2kG(x, z, z) \leq 2kG(x, z, z). \end{aligned}$$

Since $2k < 1$, we get $G(x, z, z) < G(x, z, z)$, which is a contradiction. Thus, F and g have a unique common fixed point. ■

COROLLARY 2.1. *Let (X, G) be a G_b -metric space. Let $F : X \times X \rightarrow X$ and $g : X \rightarrow X$ be two mappings such that*

$$G(F(x, y), F(u, v), F(u, v)) \leq \frac{k}{s^2}(G(gx, gu, gu) + G(gy, gv, gv)) \quad (3)$$

for all $x, y, u, v \in X$. Assume F and g satisfy the following conditions:

1. $F(X \times X) \subseteq g(X)$,
2. $g(X)$ is complete, and
3. g is continuous and commutes with F .

If $k \in (0, \frac{1}{2})$, then there is a unique x in X such that $gx = F(x, x) = x$.

Proof. Follows from Theorem 2.1 by taking $z = u$, $v = w$ and $\phi(t) = kt$. ■

COROLLARY 2.2. *Let (X, G) be a complete G_b -metric space. Let $F : X \times X \rightarrow X$ be a mapping such that*

$$G(F(x, y), F(u, v), F(u, v)) \leq \frac{k}{s^2}(G(x, u, u) + G(y, v, v))$$

for all $x, y, u, v \in X$. If $k \in [0, \frac{1}{2})$, then there is a unique x in X such that $F(x, x) = x$.

REMARK 2.1. Since every G_b -metric is a G -metric when $s = 1$, so our results can be viewed as generalizations and extensions of corresponding results in [35] and several other comparable results.

Now, we introduce some examples for Theorem 2.1.

Example 2.1. Let $X = [0, 1]$. Define $G : X \times X \times X \rightarrow \mathbb{R}^+$ by

$$G(x, y, z) = (|x - y| + |x - z| + |y - z|)^2$$

for all $x, y, z \in X$. Then (X, G) is a complete G_b -metric space with $s = 2$, according to Example 1.1. Define a map $F : X \times X \rightarrow X$ by $F(x, y) = \frac{x}{128} + \frac{y}{256}$ for $x, y \in X$.

Also, define $g : X \rightarrow X$ by $g(x) = \frac{x}{4}$ for $x \in X$ and $\phi(t) = \frac{t}{4}$ for $t \in \mathbb{R}^+$. We have

that

$$\begin{aligned}
& G(F(x, y), F(u, v), F(z, w)) \\
&= (|F(x, y) - F(u, v)| + |F(u, v) - F(z, w)| + |F(z, w) - F(x, y)|)^2 \\
&= \left(\left| \frac{x}{128} + \frac{y}{256} - \frac{u}{128} - \frac{v}{256} \right| + \left| \frac{u}{128} + \frac{v}{256} - \frac{z}{128} - \frac{w}{256} \right| \right. \\
&\quad \left. + \left| \frac{z}{128} + \frac{w}{256} - \frac{x}{128} - \frac{y}{256} \right| \right)^2 \\
&\leq \left(\frac{1}{128} |x - u| + \frac{1}{256} |y - v| + \frac{1}{128} |u - z| + \frac{1}{256} |v - w| + \frac{1}{128} |z - x| \right. \\
&\quad \left. + \frac{1}{256} |w - y| \right)^2 \\
&= \left(\frac{1}{32} \left(\left| \frac{x}{4} - \frac{u}{4} \right| + \left| \frac{u}{4} - \frac{z}{4} \right| + \left| \frac{z}{4} - \frac{x}{4} \right| \right) + \frac{1}{64} \left(\left| \frac{y}{4} - \frac{v}{4} \right| + \left| \frac{v}{4} - \frac{w}{4} \right| + \left| \frac{w}{4} - \frac{y}{4} \right| \right) \right)^2 \\
&\leq \frac{2}{32^2} \left(\left| \frac{x}{4} - \frac{u}{4} \right| + \left| \frac{u}{4} - \frac{z}{4} \right| + \left| \frac{z}{4} - \frac{x}{4} \right| \right)^2 + \frac{2}{64^2} \left(\left| \frac{y}{4} - \frac{v}{4} \right| + \left| \frac{v}{4} - \frac{w}{4} \right| + \left| \frac{w}{4} - \frac{y}{4} \right| \right)^2 \\
&= \frac{2}{32^2} G(gx, gu, gz) + \frac{2}{64^2} G(gy, gv, gw) \\
&\leq \frac{2}{32^2} (G(gx, gu, gz) + G(gy, gv, gw)) \\
&\leq \frac{1}{4} \frac{G(gx, gu, gz) + G(gy, gv, gw)}{4} \\
&= \frac{1}{2^2} \phi(G(gx, gu, gz) + G(gy, gv, gw))
\end{aligned}$$

holds for all $x, y, u, v, z, w \in X$. It is easy to see that F and g satisfy all the hypothesis of Theorem 2.1. Thus F and g have a unique common fixed point. Here $F(0, 0) = g(0) = 0$. ■

EXAMPLE 2.2. Let X and G be as in Example 2.1. Define a map

$$F : X \times X \rightarrow X \quad \text{by} \quad F(x, y) = \frac{1}{16}x^2 + \frac{1}{16}y^2 + \frac{1}{8}$$

for $x, y \in X$. Then $F(X \times X) = [\frac{1}{8}, \frac{1}{4}]$. Also,

$$\begin{aligned}
& G(F(x, y), F(u, v), F(u, v)) \\
&= (2|F(x, y) - F(u, v)|)^2 = \frac{1}{64}(|x^2 - u^2 + y^2 - v^2|)^2 \\
&\leq \frac{1}{64}(|x^2 - u^2| + |y^2 - v^2|)^2 \leq \frac{1}{32}(|x^2 - u^2|^2 + |y^2 - v^2|^2) \\
&\leq \frac{1}{32}(4|x - u|^2 + 4|y - v|^2) = \frac{1}{32}(G(x, u, u) + G(y, v, v)) \\
&\leq \frac{1}{2^2}(G(x, u, u) + G(y, v, v))
\end{aligned}$$

Then by Corollary 2.2, F has a unique fixed point. Here $x = 4 - \sqrt{15}$ is the unique fixed point of F , that is, $F(x, x) = x$. ■

Now we present an example for the main result in an asymmetric G_b -metric space.

EXAMPLE 2.3. Let $X = \{0, 1, 2\}$ and let

$$A = \{(2, 0, 0), (0, 2, 0), (0, 0, 2)\}, \quad B = \{(2, 2, 0), (2, 0, 2), (0, 2, 2)\}$$

$$\text{and } C = \{(x, x, x) : x \in X\}.$$

Define $G : X^3 \rightarrow \mathbb{R}^+$ by

$$G(x, y, z) = \begin{cases} 1, & \text{if } (x, y, z) \in A \\ 3, & \text{if } (x, y, z) \in B \\ 4, & \text{if } (x, y, z) \in X^3 - (A \cup B \cup C) \\ 0, & \text{if } x = y = z. \end{cases}$$

It is easy to see that (X, G) is an asymmetric G_b -metric space with coefficient $s = \frac{3}{2}$. Also, (X, G) is complete. Indeed, for each (x_n) in X such that $G(x_n, x_m, x_m) \rightarrow 0$, then there is a $k \in \mathbb{N}$ such that for each $n \geq k$, $x_n = x_m = x$ for an $x \in X$, so $G(x_n, x_n, x) \rightarrow 0$.

Define mappings F and g by

$$F = \begin{pmatrix} (0, 0) & (0, 1) & (1, 0) & (1, 1) & (1, 2) & (2, 1) & (2, 2) & (2, 0) & (0, 2) \\ 0 & 2 & 0 & 0 & 0 & 0 & 0 & 0 & 2 \end{pmatrix},$$

$$g = \begin{pmatrix} 0 & 1 & 2 \\ 0 & 2 & 2 \end{pmatrix}.$$

We see that $F(X \times X) \subseteq gX$, g is continuous and commutes with F , and $g(X)$ is complete.

Define $\phi : [0, \infty) \rightarrow [0, \infty)$ by $\phi(t) = \frac{27}{4} \ln(\frac{2t}{27} + 1)$. Since

$$(F(x, y), F(u, v), F(z, w)), (gx, gu, gz), (gy, gv, gw) \in A \cup B,$$

we have

$$G(F(x, y), F(u, v), F(z, w)), G(gx, gu, gz), G(gy, gv, gw) \in \{0, 1, 3\}.$$

Hence, one can easily check that the contractive condition (2) is satisfied for every $x, y, z, u, v, w \in X$.

Thus, all the conditions of Theorem 2.1 are fulfilled and F and g have a unique common fixed point. Here $F(0, 0) = g(0) = 0$. ■

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